

ICESTARS

Estimation of Initial Conditions for Harmonic Balance Oscillator Analysis of Free-Running Oscillators

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Introduction to Oscillator Analysis

Start-up of an Oscillator (TRANSient simulation)

Colpitts Oscillator

VCOBi Oscillator

HB Oscillator Analysis in the APLAC Simulator

Algorithms for Estimating the Initial Conditions

FFT-based Method

Zero-Crossings Method

Simulation Results

Conclusions and Further Improvements

New Newton method using generalized eigenvalues

Conclusions new Newton method



Introduction to Oscillator Analysis

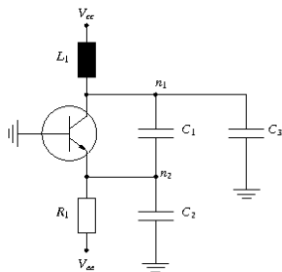
- ▶ Oscillator is an autonomous circuit, no periodic excitation
 - ▶ Only DC bias sources connected to the circuit
- ▶ Transient analysis of an oscillator
 - ▶ Oscillation starts by itself due to noise or instability
 - ▶ Long start-up time \Rightarrow long simulation time
 - ▶ Suitable for highly nonlinear oscillators
- ▶ HB analysis of an oscillator
 - ▶ May converge to DC solution (no periodic excitation!)
 - ▶ Need to either modify HB equation to be solved, or apply artificial excitation
 - ▶ Oscillation frequency, i.e, fundamental HB frequency, is unknown
- ▶ Why use HB instead of transient analysis ?
 - ▶ HB is needed for (phase) noise simulations
 - ▶ Frequency dependent linear devices (S-parameters, ...)



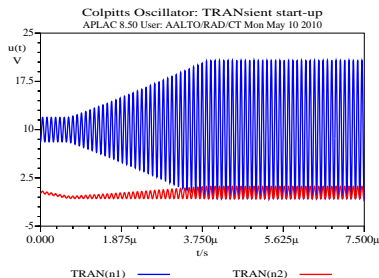
Start-up of an Oscillator (TRANSient simulation)

Colpitts Oscillator

Colpitts: $f_{osc}=10.007$ MHz



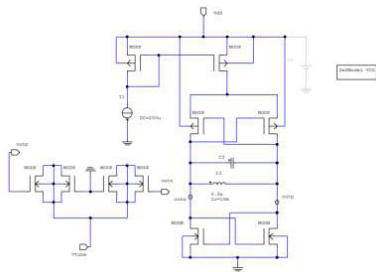
Steady-state:
40 periods of f_{osc}



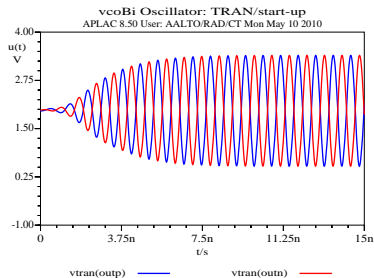
Start-up of an Oscillator (TRANsient simulation)

VCOBi Oscillator

VCOBi: $f_{osc}=1.23$ GHz



Steady-state:
7 periods of f_{osc}



HB Oscillator Analysis in the APLAC Simulator

- ▶ HB Oscillator analysis is done using optimization; variables are oscillation frequency, f_{osc} , and oscillation amplitude, v_{osc}



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- ▶ Oscillator analysis algorithm
 - 1) Change optimization variables f_{osc} , v_{osc}
 - 2) HB analysis (incl. nonlinear iteration)
 - 3) Compute optimization goal
 - 4) Terminate optimization if in specs, otherwise goto 1)

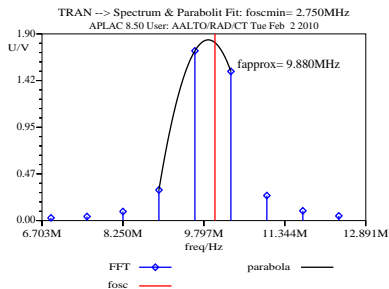


Algorithms for Estimating the Initial Conditions

- ▶ Two algorithms for finding better initial estimate for the oscillator analysis are presented
 - ▶ FFT-based Method (search for the most dominant spectral line)
 - ▶ Zero-Crossings Method (estimate frequency based on zero crossings) – Related to Poincaré Map method
- ▶ Both of these methods use the data from the transient simulation, length of the period is $1/\text{foscinit}$ (initial value of fosc):
 - ▶ transient analysis is first run up to five periods;
 - ▶ continue transient for one period, and store the probe element voltage waveform
- ▶ Transient start-up can be accelerated by injecting a short $\cos()$ -like pulse (length less than one period)

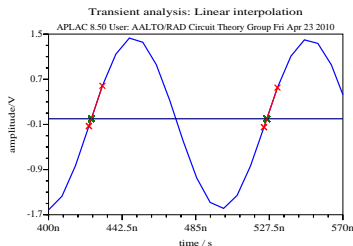
FFT-based Method

- a) First, do FFT for the transient voltage waveform
- b) Search for the most dominant spectral component at non-zero frequency, and
- c) a parabola (second order polynomial) is fitted to the most dominant and neighboring spikes at both sides, and
- d) the maximum of the parabola is computed
- e) \Rightarrow this method can be used to find both frequency and oscillation amplitude



Zero-Crossings Method

- a) First, the average value or half of the maximum swing is removed from the collected time-domain data, and
- b) zero-crossings are searched from the data
- c) Accuracy can be improved by applying linear or spline interpolation, i.e., interpolation is done for 1-2 data points on both sides of the zero-crossing location
- d) Oscillation amplitude can be estimated from the maximum swing



Comparison of Implemented Methods

VCOBi oscillator: $f_{osc}=1.23$ GHz, $v_{osc}=1.43$ V, $t_0=5/f_{osc}$ init

method	HBITER	CPU[s]	estimated fosc[GHz]	estimated vosc[V]
old	1116	3.1	1.0	1.0
FFT/1	58	0.1	1.11	0.945
FFT/2	1487	4.0	1.13	0.948
ZeroC/1	23	0.06	1.23	1.36
ZeroC/2	31	0.08	1.22	1.41

- /1 set fosc and vosc, spectral voltages from transient simulation
- /2 use initial pulse and /1

AWR VCO: $f_{osc}=3.25$ GHz, $v_{osc}=1.25$ V

circuit size: 40xBSIM3, 80xJuncap diode

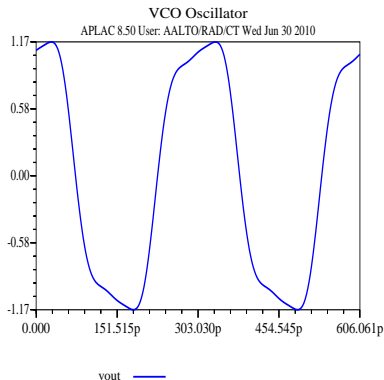
Initial values:

$f_{osc}=3.0$ GHz, $v_{osc}=1.0$ V

method	HBITER	CPU[s]
old	2259	110.6
TAHB	48	2.7
FFT	47	6.2
ZeroC	31	1.4

Estimated f_{osc} and v_{osc} :

FFT	2.7 GHz	1.09 V
ZeroC	3.1 GHz	1.17 V



Conclusions and Further Improvements

- ▶ Usage of these new methods improves reliability and robustness of HB oscillator analysis: User does not need to supply accurate initial values
- ▶ Zero-Crossing methods seems to be better than FFT method (Q: Multiple crossings?)
- ▶ Optimization algorithms are quite sensitive to the formulation of the optimization goal and simulation set-up. Better initial estimate does not always result in faster convergence in optimization and/or HB analysis
- ▶ TODO: tune optimization algorithm and/or parameters more suitable for oscillator optimization
- ▶ TODO: add more adaptivity, currently initial transient is optionally continued until estimate of v_{osc} is within user-specified limits



New Newton method for PSS

DAE-system of equations on $[0, T]$

$$\frac{dq(x)}{dt} + j(x) = \vec{0} \in \vec{R}^N,$$

where $x = x(t)$, $x(0) = x(T)$, q and j are known functions of x .

Transforming to $[0, 1] \implies f = 1/T$
explicit unknown

$$f \frac{dq(x)}{dt} + j(x) = 0.$$

One usually requires $p^T x - c = 0$
 \implies which p , which c ?
Usually left to the user ...

Simpson's Rule un $[t_{i-1}, t_{i+1}]$

$$F(X^k) = \begin{bmatrix} x_0 - x_N \\ \frac{f(q_2 - q_0)}{2\Delta t} + \frac{(j_0 + 4j_1 + j_2)}{6} \\ \vdots \\ \frac{f(q_1 - q_{N-1})}{2\Delta t} + \frac{(j_{N-1} + 4j_N + j_1)}{6} \end{bmatrix} =$$

Newton:

$$M^k \begin{bmatrix} \Delta X^k \\ \Delta f^k \end{bmatrix} = - \begin{bmatrix} F(X^k, f^k) \\ p^T X^k - c \end{bmatrix}$$

$$M^k = \begin{bmatrix} Y^k & b^k \\ p^T & \delta \end{bmatrix}$$

$$Y^k = \frac{\partial F}{\partial x} = f \cdot C + G, \quad b^k = \frac{\partial F}{\partial f}$$

- how dynamically improve p , c ?

Use of generalized eigenvalues

- Observ. 1: Y nearly singular in the limit $\implies p$ and b such that M non-singular. c must be in a proper range.
- Observ. 2: $x'_{\text{PSS}}(t)$ satisfies linearized equations.

Generalized eigenvalues for matrix pencils:

- DPA [Dominant Pole Algorithm]
- RQI [Rayleigh Quotient Iteration]

Eigen triples $[v, w, \lambda]$ for λ closest to 1

$$[\lambda f \times C + G]v = 0, w^T[\lambda f \times C + G] = 0$$

Biorthogonality relation $w^T C v = 1 \implies$ new gauge equation

$$w^T \Big|_{x=x^k} \cdot C \cdot \frac{dX}{dt} \Big|_{x=x^k} - 1 = 0.$$

$dX/dt = DX$ [spectral differentiation]

No information about solution needed

Benchmark problem

$$\begin{aligned}\frac{\partial y}{\partial t} &= z + \varepsilon h(y, z) y, \\ \frac{\partial z}{\partial t} &= -y + \varepsilon h(y, z) z.\end{aligned}$$

$\varepsilon = 0.1$

$$h(y, z) = 1 - \sqrt{y^2 + z^2}$$

Initial conditions:

$$T_0 = 1.1 \times (2\pi)$$

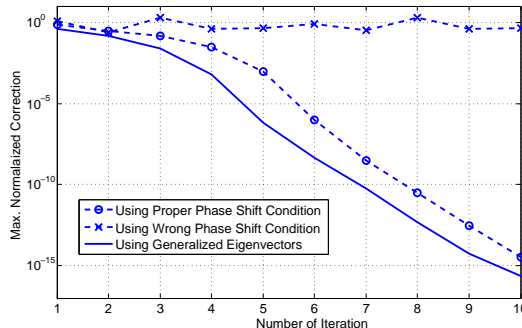
$$y_0(t) = 1.5 \sin(t + \pi/4)$$

$$z_0(t) = \cos(t)$$

100 time points

Compare Gauge equations:

- Using c outside range of $x(t)$
- Using better c
- Using generalized eigenvalues



Conclusions new Newton method

- ▶ Traditional methods require knowledge by the user:
 - Location of the oscillator solution (p)
 - Range of values of the oscillator solution (c)
- ▶ Generalized eigenvalue methods dynamically provide a new gauge equation
- ▶ Spectral differentiation of $x(t)$ is natural in Harmonic Balance
- ▶ New approach looks robust
- ▶ TODO: tests needed on larger oscillator circuits

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