

# Modeling and numerical analysis of coupled circuit and electromagnetic simulation

Minisymposia: Integrated Circuit/EM Simulation and Design  
Technologies for Radio Systems II

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# Outline

- 1 DAE formulation
- 2 Circuit-Device Model
- 3 Structural Properties
- 4 Outlook

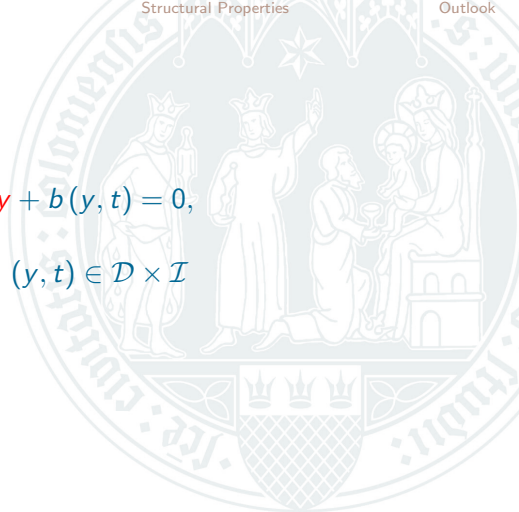


# DAE formulation

Regarding

$$A(y, t) \frac{d}{dt} y + b(y, t) = 0,$$

where  $A(y, t)$  is singular for all  $(y, t) \in \mathcal{D} \times \mathcal{I}$

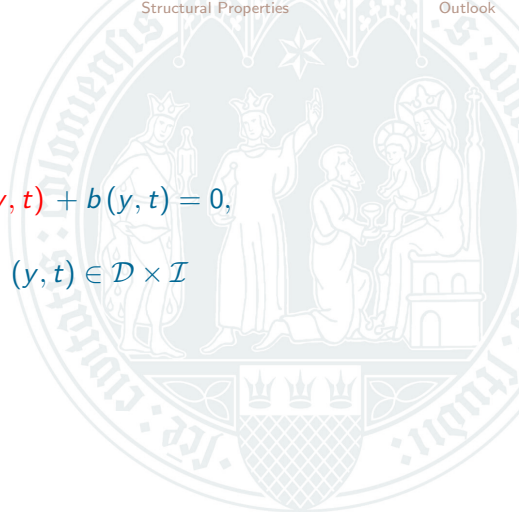


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We speak of a **properly stated leading term** if

$$\ker A(\cdot) \oplus \operatorname{im} d_y(\cdot) = \mathbb{R}^n$$

and there is a projector  $R(t) \in \mathcal{C}^1(\mathcal{I}, \mathbb{R}^n)$  with

$$\ker A(\cdot) = \ker R(t) \text{ and } \operatorname{im} d_y(\cdot) = \operatorname{im} R(t).$$



# Properly stated leading term

- Introduced in [März 2002]



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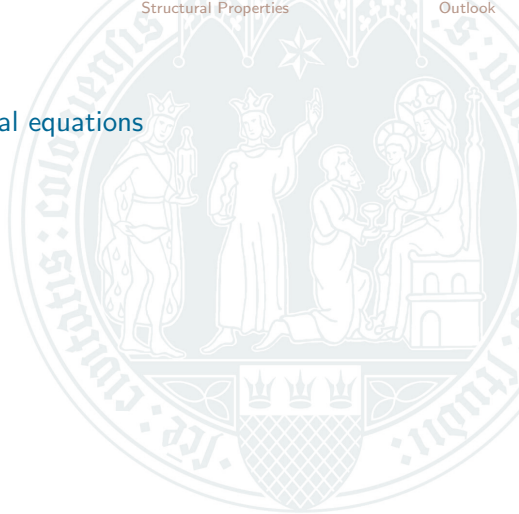
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- DAEs are mostly not formulated in that form
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- leading term  $d(\cdot)$  figures out which derivatives are involved
- for a class of DAEs the BDF and RK methods are stability preserving [Higuera, März, Tischendorf 2003].



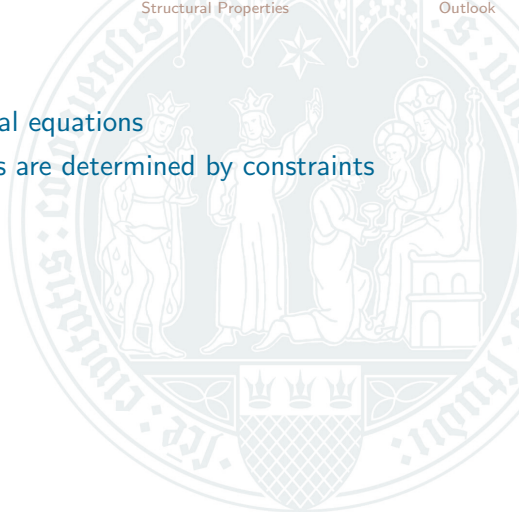
# ODE vs. DAE

- implicit ordinary differential equations



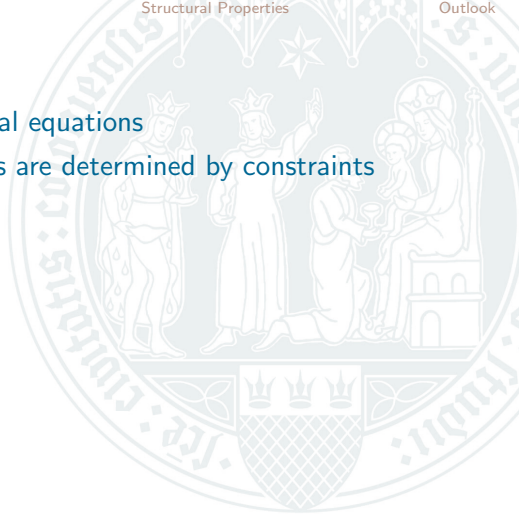
# ODE vs. DAE

- implicit ordinary differential equations
- some solution components are determined by constraints



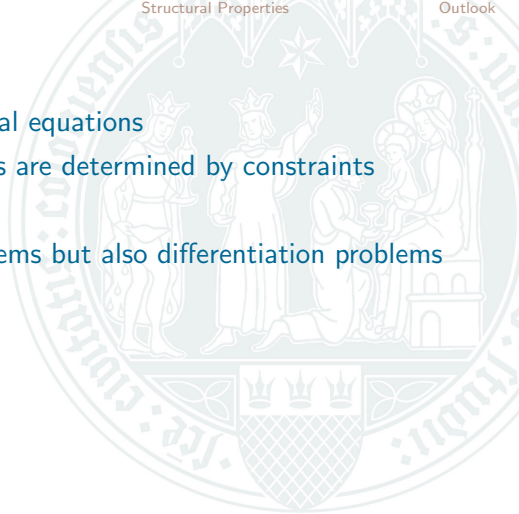
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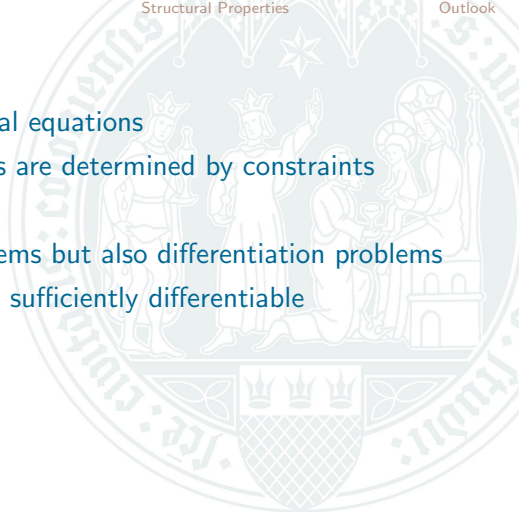
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- not only integration problems but also differentiation problems



# ODE vs. DAE

- implicit ordinary differential equations
- some solution components are determined by constraints
- restriction of initial values
- not only integration problems but also differentiation problems
- parts of the DAE must be sufficiently differentiable





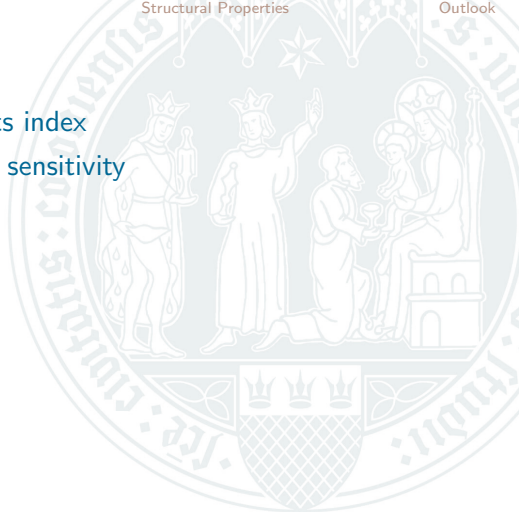
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- measure of the equation's sensitivity



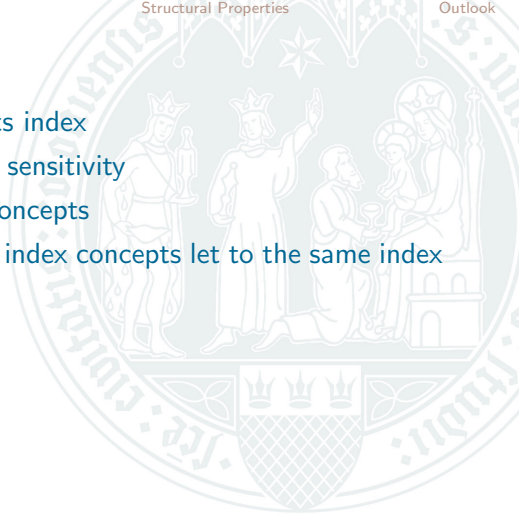
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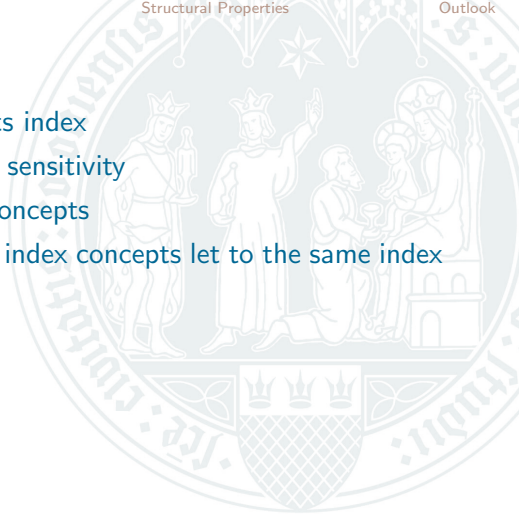
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- using tractability index



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- in the linear case different index concepts let to the same index
- using tractability index
- require low smoothness and is algorithmic



# Modified Nodal Analysis

$$A_C \frac{d}{dt} q(A_C^T \mathbf{e}, t) + A_R g(A_R^T \mathbf{e}, t) + A_L j_L + A_V j_V + A_I i_s(t) = 0,$$

$$\frac{d}{dt} \phi(j_L, t) - A_L^T \mathbf{e} = 0,$$

$$A_V^T \mathbf{e} - v_s(t) = 0,$$

where

- $v_s(t)$ ,  $i_s(t)$ ,  $q(\cdot)$ ,  $g(\cdot)$ ,  $\phi(\cdot)$  given functions,



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# Maxwell's equation

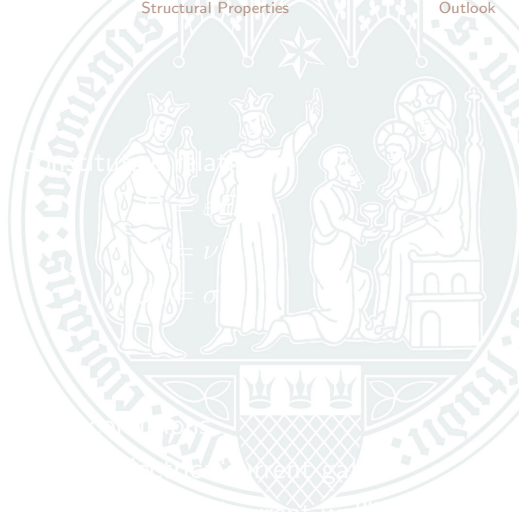
Law's

$$\nabla \cdot D = \rho$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial}{\partial t} B$$

$$\nabla \times H = J_c + \frac{\partial}{\partial t} D$$



# Maxwell's equation

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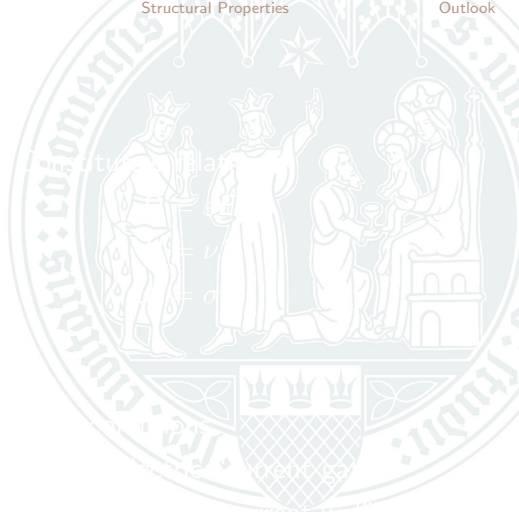
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Continuity equation

$$\nabla \cdot J_c + \nabla \cdot \frac{\partial}{\partial t} D = 0$$



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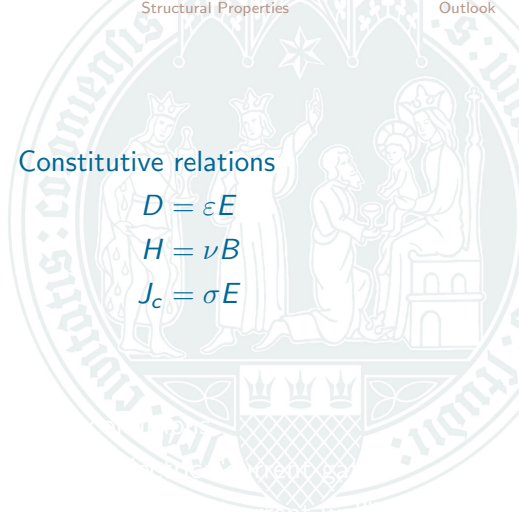
$$D = \varepsilon E$$

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Boundary conditions

electric: "current gate"

magnetic: "current wall"

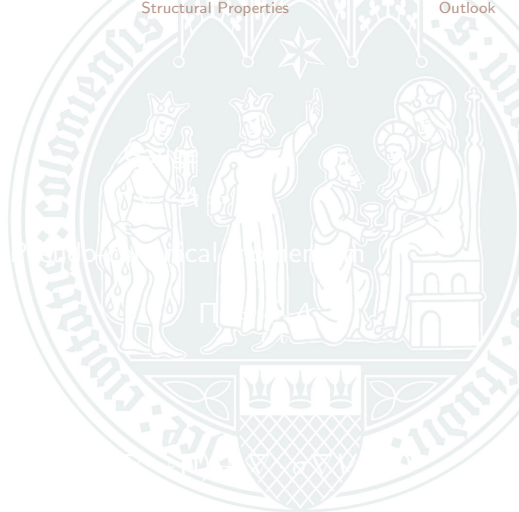


# Potentials

Scalar and vector potential

$$E = -\nabla V - \frac{\partial}{\partial t} A$$

$$B = \nabla \times A$$



# Potentials

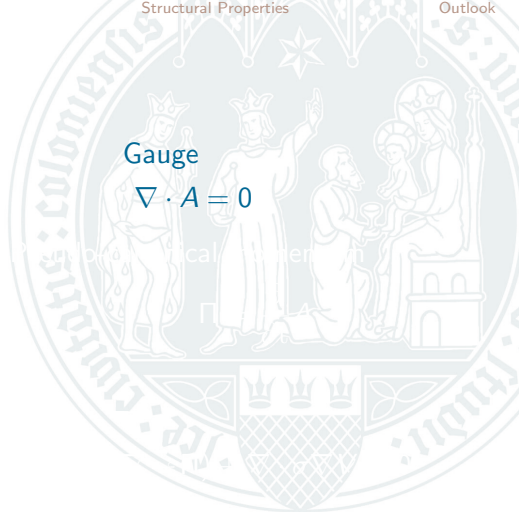
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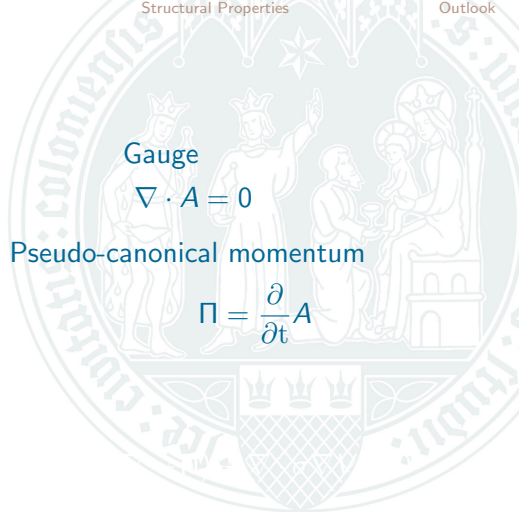
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Pseudo-canonical momentum

$$\Pi = \frac{\partial}{\partial t} A$$



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Gauge

$$\nabla \cdot A = 0$$

Pseudo-canonical momentum

$$\Pi = \frac{\partial}{\partial t} A$$

Potential formulation

$$\frac{\partial}{\partial t} (\nabla \cdot \varepsilon \nabla V + \nabla \cdot \sigma A + \nabla \cdot \varepsilon \Pi) + \nabla \cdot \sigma \nabla V = 0$$

$$\frac{\partial}{\partial t} (\varepsilon \nabla V + \sigma A + \varepsilon \Pi) + \sigma \nabla V + \nabla \times \nu \nabla \times A - \nu \nabla \nabla \cdot A = 0$$

$$\frac{\partial}{\partial t} A - \Pi = 0$$





# FIT space discretization

$$\frac{\partial}{\partial t} (\nabla \cdot \varepsilon \nabla V + \nabla \cdot \sigma A + \nabla \cdot \varepsilon \Pi) + \nabla \cdot \sigma \nabla V = 0$$

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- consistent formulation for the discrete Maxwell's equations



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- discr. operators contains only topological information



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$$\frac{\partial}{\partial t} A - \Pi = 0$$

- consistent formulation for the discrete Maxwell's equations
- error only in the constitutive relations
- discr. operators contains only topological information
- need two grids



# FIT space discretization

$$\frac{d}{dt} \left( \tilde{\mathbf{S}}\mathbf{M}_\varepsilon\mathbf{G}\mathbf{v} + \tilde{\mathbf{S}}\mathbf{M}_\sigma\mathbf{a} + \tilde{\mathbf{S}}\mathbf{M}_\varepsilon\boldsymbol{\pi} \right) + \tilde{\mathbf{S}}\mathbf{M}_\sigma\mathbf{G}\mathbf{v} = 0$$

$$\frac{d}{dt} \left( \mathbf{M}_\varepsilon\mathbf{G}\mathbf{v} + \mathbf{M}_\sigma\mathbf{a} + \mathbf{M}_\varepsilon\boldsymbol{\pi} \right) + \mathbf{M}_\sigma\mathbf{G}\mathbf{v} + \tilde{\mathbf{C}}\mathbf{M}_\nu\mathbf{C}\mathbf{a} - \mathbf{M}_\nu\mathbf{G}\mathbf{S}\mathbf{a} = 0$$

$$\frac{d}{dt} \mathbf{a} - \boldsymbol{\pi} = 0$$

- $V \rightarrow \mathbf{v}$ ,  $A \rightarrow \mathbf{a}$ ,  $\Pi \rightarrow \boldsymbol{\pi}$ ,  $\varepsilon \rightarrow \mathbf{M}_\varepsilon$ ,  $\sigma \rightarrow \mathbf{M}_\sigma$  and  $\nu \rightarrow \mathbf{M}_\nu$



# FIT space discretization

$$\frac{d}{dt} \left( \tilde{\mathbf{S}} \mathbf{M}_\varepsilon \mathbf{G} \mathbf{v} + \tilde{\mathbf{S}} \mathbf{M}_\sigma a + \tilde{\mathbf{S}} \mathbf{M}_\varepsilon \pi \right) + \tilde{\mathbf{S}} \mathbf{M}_\sigma \mathbf{G} \mathbf{v} = 0$$

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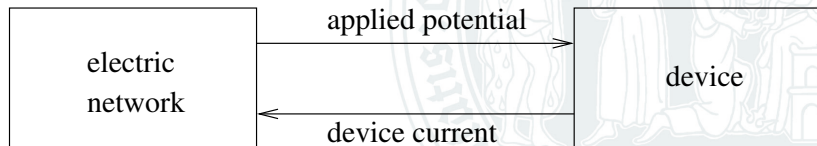
$$\frac{d}{dt} a - \pi = 0$$

- $V \rightarrow v, A \rightarrow a, \Pi \rightarrow \pi, \varepsilon \rightarrow \mathbf{M}_\varepsilon, \sigma \rightarrow \mathbf{M}_\sigma$  and  $\nu \rightarrow \mathbf{M}_\nu$
- $\nabla \rightarrow \mathbf{G}, \tilde{\mathbf{G}}, \nabla \times \rightarrow \mathbf{C}, \tilde{\mathbf{C}}$  and  $\nabla \cdot \rightarrow \mathbf{S}, \tilde{\mathbf{S}}$



# Coupling Conditions

Coupling via boundary conditions and source term.



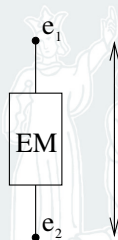


# Coupling Conditions

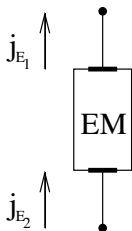
Dirichlet boundary condition for  $V$ :

$$V = V(x, A_E^T e)$$

where  $A_E$  describes the circuit topology and  $A_E^T e$  the potential difference.



# Coupling Conditions



Current through the  $k$ -th contact:

$$\mathbf{j}_{E_k} = \int_{\Gamma_k} \mathbf{J}_t \cdot \boldsymbol{\nu} \, ds$$

where  $\mathbf{J}_t = r(V, A, \Pi)$  is linear.

## Coupled System

$$A_C \frac{d}{dt} q(A_C^\top e, t) + A_R g(A_R^\top e, t) + A_{IJL} + A_V j_V + A_I i_s(t) + A_L = 0,$$

$$\frac{d}{dt} \phi(j_L, t) - A_L^\top e = 0,$$

$$A_V^\top e - v_s(t) = 0$$

where

- $v_s(t)$ ,  $i_s(t)$ ,  $q(\cdot)$ ,  $g(\cdot)$ ,  $\phi(\cdot)$  given functions,
- incidence matrices  $[A_V \ A_I \ A_C \ A_R \ A_L \ ]$



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$$\frac{d}{dt} \phi(j_L, t) - A_L^\top e = 0,$$

$$A_V^\top e - v_s(t) = 0,$$

$$j_E + f\left(A_E^\top \frac{de}{dt}, \frac{dv}{dt}, \frac{da}{dt}, \frac{d\pi}{dt}, A_E^\top e, v\right) = 0,$$

$$h\left(A_E^\top \frac{de}{dt}, \frac{dv}{dt}, \frac{da}{dt}, \frac{d\pi}{dt}, A_E^\top e, v, a, \pi\right) = 0$$

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- incidence matrices  $[A_V \ A_I \ A_C \ A_R \ A_L \ A_E]$
- $f(\cdot)$ ,  $h(\cdot)$  linear functions from the space discretization



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## Physical reasons and passivity

- $A_V$  and  $[A_V A_C A_R A_L]^T$  have full column rank



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- $A_V$  and  $[A_V A_C A_R A_L]^T$  have full column rank
- The functions  $q(u, t)$ ,  $g(u, t)$  and  $\phi(j, t)$  are continuous differentiable with

$$C(u, t) := \frac{\partial q(u, t)}{\partial u}$$

$$L(j, t) := \frac{\partial \phi(j, t)}{\partial j}$$

$$G(u, t) := \frac{\partial g(u, t)}{\partial u}$$

positive definite



# Index Result

## Theorem

*The coupled system after space discretization is a DAE of the form*

$$A \frac{d}{dt} d(y, t) + b(y, t) = 0$$

*with properly stated leading term. The DAE has index-2 and is unique solvable.*

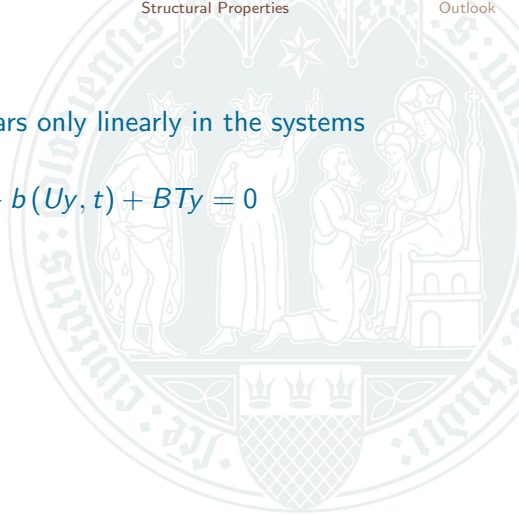




# Starting values

Index-2 components  $T_y$ : appears only linearly in the systems

$$A \frac{d}{dt} d(Uy, t) + b(Uy, t) + BT_y = 0$$



# Starting values

Index-2 components  $Ty$ : appears only linearly in the systems

$$A \frac{d}{dt} d(Uy, t) + b(Uy, t) + BTy = 0$$

Starting values:

- Non-consistent  $(z^0, y^0)$  fulfilling

$$Az^0 + b(y^0, t_0) = 0$$



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- one implicit Euler step starting with  $y^0$
- consistent value  $y_1$  at  $t + h$ .



# Outlook

- consistent value within the first step



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- consistent value within the first step
- Lorenz instead of Coulomb gauge



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- consistent value within the first step
- Lorenz instead of Coulomb gauge
- Lorenz vs. Coulomb gauge



# Outlook

- consistent value within the first step
- Lorenz instead of Coulomb gauge
- Lorenz vs. Coulomb gauge
- (tractability) index-1 result





Thanks for your attention!

